

# MA313 Linear Algebra

## Video 6: Further examples of subspaces

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## Recall

$\mathbb{P}_n = \{a_0 + a_1t + \cdots + a_nt^n : a_0, \dots, a_n \in \mathbb{R}\}$  is the vector space of polynomials of degree at most  $n$  in the variable  $t$ .

## Definition

$$\mathbb{P} := \bigcup_{n=0}^{\infty} \mathbb{P}_n = \{p(t) = a_0 + a_1t + \cdots + a_nt^n : n \geq 0; a_0, \dots, a_n \in \mathbb{R}\}$$

is the vector space of all polynomials in  $t$  (without any bounds on the degree!).

Here, the addition and scalar multiplication in  $\mathbb{P}$  are just the usual operations: we add and multiply as expected.

## Fact

- $\mathbb{P}_m$  is a subspace of  $\mathbb{P}_n$  if and only if  $m \leq n$ .
- $\mathbb{P}_n$  is a subspace of  $\mathbb{P}$  for all  $n \geq 0$ .

Note that

$$\begin{aligned}\mathbb{P}_0 &= \mathbb{R} = \text{constant polynomials} \\ &= \{p(t) \in \mathbb{P} : p'(t) = 0\}\end{aligned}$$

where the **derivative** of  $p(t) = a_0 + a_1t + \cdots + a_nt^n$  is

$$p'(t) = a_1 + 2a_2t + \cdots + na_nt^{n-1}.$$

More generally,

$$\mathbb{P}_n = \left\{ p(t) \in \mathbb{P} : p^{(n+1)}(t) = 0 \right\}.$$

**Punchline:** the subspaces  $\mathbb{P}_n$  of  $\mathbb{P}$  can be described as solutions of certain equations!

## Example

Let  $\mathbb{D} \subseteq \mathbb{R}$  be a subset. Let  $V$  be the vector space of all functions  $\mathbb{D} \rightarrow \mathbb{R}$  from before.

Recall:

- $(f + g)(x) = f(x) + g(x)$  for  $f, g \in V$  and  $x \in \mathbb{D}$
- $(cf)(x) = cf(x)$  for  $f \in V$  and  $c \in \mathbb{R}$

Let

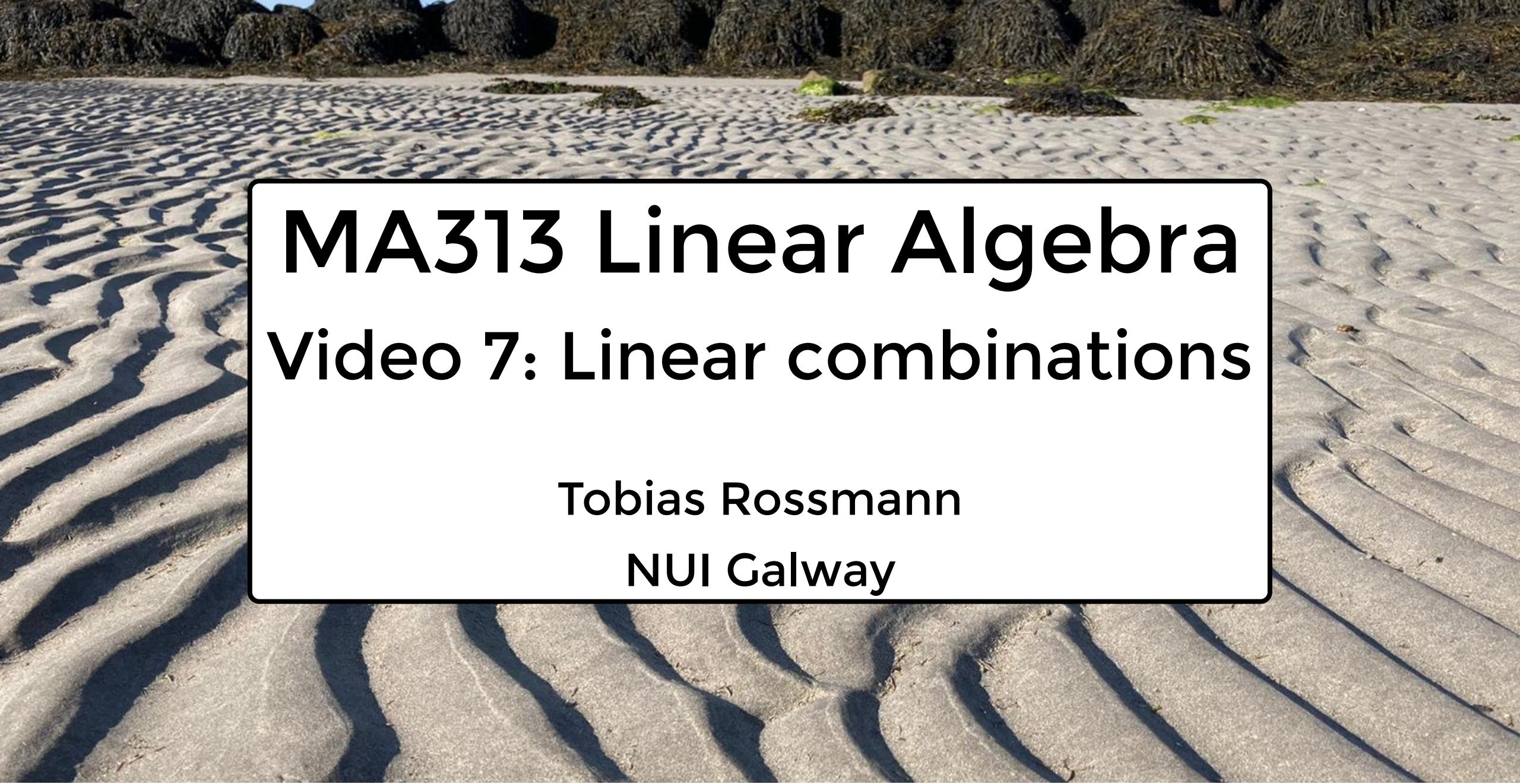
$$C(\mathbb{D}) := \{f: \mathbb{D} \rightarrow \mathbb{R} : f \text{ is continuous}\} \subseteq V.$$

## Theorem

$C(\mathbb{D})$  is a subspace of  $V$ .

Why? Calculus!

- Constant functions are continuous. In particular, the zero vector of  $V$  (= the constant function with value zero) belongs to  $C(\mathbb{D})$ .
- Sums and products of continuous functions are continuous. Hence,  $C(\mathbb{D})$  is closed under addition and scalar multiplication (= multiplication by constant functions).



# MA313 Linear Algebra

## Video 7: Linear combinations

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## Question

How can we describe *all* subspaces of a given vector space?

## Example

There are precisely three types of subspaces of  $\mathbb{R}^2$ :

- $\{0\}$ ,
- $\mathbb{R}^2$ , and
- lines through the origin.

## Question

How do subspaces arise in "nature"?

- **From the top:**  
all vectors that have "suitable properties"
- **From the bottom:**  
start with some collection of vectors and consider the subspace that they "span"

## Definition

A **linear combination** of vectors  $u_1, \dots, u_p$  in some vector space is a vector of the form

$$c_1 u_1 + \dots + c_p u_p$$

for scalars  $c_1, \dots, c_p \in \mathbb{R}$ .

## Example

In  $\mathbb{R}^2$ ,  $\begin{bmatrix} 2 \\ -3 \end{bmatrix}$  is a linear combination of  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

## Example

Is  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  a linear combination of  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$  and  $\begin{bmatrix} -4 \\ -6 \end{bmatrix}$  in  $\mathbb{R}^2$ ?